



LUINICAL	SPECIFICATIONS			
· LOIMIOA	Channel	1408		
GNSS Configuration		GPS: L1C/A, L1C, L2P(Y), L2C, L5		
	GNSS Signal	BDS: B1I, B2I, B3I, B1C, B2a, B2b		
		GLONASS: L1, L2, L3		
		GALILEO: E1, E5a, E5b, E6		
		QZSS: L1, L2, L5, L6		
		NavIC: L5		
		SBAS: L1, L2, L5		
	PPP: B2b-PPP, E6-HAS			
	Output format	ASCII: NMEA-0183, Binary		
	Output rate	1Hz~20Hz		
	Static data format	GNS, Rinex		
	Real Time Kinematic	RTCM2.X, RTCM3.X		
	Network Mode	VRS, FKP, MAC, Support NTRIP protocol		
System	Operation system	Linux		
Configuration	Storage	Circulating 512GB ROM		
-			V/ 2 5 mans 1 0 4 mms DMC	
Accuracy and Reliability[2]	High-Precision Static	H: 2.5 mm + 0.1 ppm RMS	V: 3.5 mm + 0.4 ppm RMS	
	Static and Fast Static PPK	H: 2.5 mm + 0.5ppm RMS	V: 5 mm + 0.5ppm RMS	
		H: 8mm + 1ppm RMS	V: 15mm + 1ppm RMS V: 20cm	
	PPP	H: 10cm H: ±0.25m+1ppm RMS	V: ±0.5m+1ppm RMS	
	Code Differential GNSS Positioning	SBAS: 0.5m (H), 0.85m (V)	V. ±0.5111+ 1PP111 KWS	
	GIVEO I Calcioning		Vi. 45 mm L 4 mm m DMC	
	Real Time Kinematic (RTK)	H: 8mm+1ppm RMS	V: 15mm+1ppm RMS	
	, ,	Initialization time: Typically <10s	Initialization reliability: Typically > 99.9%	
	Tilt Survey Performance[3]	8mm+0.7mm/°tilt		
	AR stakeout	Support		
	Non-contact measurement	A single photo can acquire multiple point coordinates, with an accuracy of better than 5cm within 15 meters		
	Mesurement without GNSS signal	Absolute accuracy of 5 cm for 10 minutes even if satellite signal is lost		
		Supports		
	Real-time accuracy evaluation	Supports		
Camera	•	Supports 3 Professional Dual HD Cameras		
Camera	evaluation Pixel Function	3 Professional Dual HD Cameras Support AR stakeout, image measurement, worki	ng distance 2~15m	
Camera	evaluation Pixel Function Range	3 Professional Dual HD Cameras Support AR stakeout, image measurement, worki	ng distance 2~15m	
	evaluation Pixel Function Range Laser product classification	3 Professional Dual HD Cameras Support AR stakeout, image measurement, worki 40m Class 1 Eye Safe	ng distance 2~15m	
Camera Laser Scanner	evaluation Pixel Function Range Laser product classification FOV	3 Professional Dual HD Cameras Support AR stakeout, image measurement, worki 40m Class 1 Eye Safe H: 160° V: 59°	ng distance 2~15m	
	evaluation Pixel Function Range Laser product classification FOV Point cloud thickness	3 Professional Dual HD Cameras Support AR stakeout, image measurement, worki 40m Class 1 Eye Safe H: 160° V: 59° 2cm		
	evaluation Pixel Function Range Laser product classification FOV Point cloud thickness I/O Interface	3 Professional Dual HD Cameras Support AR stakeout, image measurement, worki 40m Class 1 Eye Safe H: 160° V: 59° 2cm USB type C port; SMA antenna port; Nano SIM ca		
	evaluation Pixel Function Range Laser product classification FOV Point cloud thickness I/O Interface Network	3 Professional Dual HD Cameras Support AR stakeout, image measurement, worki 40m Class 1 Eye Safe H: 160° V: 59° 2cm USB type C port; SMA antenna port; Nano SIM ca	ard slot	
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Laser Scanner	evaluation Pixel Function Range Laser product classification FOV Point cloud thickness I/O Interface Network WiFi	3 Professional Dual HD Cameras Support AR stakeout, image measurement, workid 40m Class 1 Eye Safe H: 160° V: 59° 2cm USB type C port; SMA antenna port; Nano SIM cand TDD-LTE, FDD-LTE, GSM IEEE 802.11a/b/g/n/ac/ax, 2.4GHz/5GHz, Wifi F	ard slot	
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Laser Scanner	evaluation Pixel Function Range Laser product classification FOV Point cloud thickness I/O Interface Network WiFi Bluetooth Internal UHF Radio	3 Professional Dual HD Cameras Support AR stakeout, image measurement, worki 40m Class 1 Eye Safe H: 160° V: 59° 2cm USB type C port; SMA antenna port; Nano SIM ca TDD-LTE, FDD-LTE, GSM IEEE 802.11a/b/g/n/ac/ax, 2.4GHz/5GHz, Wifi h Bluetooth 5.2 Power: 0.5W/1W Adjustable Frequence: 410M	ard slot notspot MHz~470MHz	
Laser Scanner Communication	evaluation Pixel Function Range Laser product classification FOV Point cloud thickness I/O Interface Network WiFi Bluetooth Internal UHF Radio Electronic bubble	3 Professional Dual HD Cameras Support AR stakeout, image measurement, worki 40m Class 1 Eye Safe H: 160° V: 59° 2cm USB type C port; SMA antenna port; Nano SIM ca TDD-LTE, FDD-LTE, GSM IEEE 802.11a/b/g/n/ac/ax, 2.4GHz/5GHz, Wifi h Bluetooth 5.2 Power: 0.5W/1W Adjustable Frequence: 410M Protocol: HI-TARGET, TRIMTALK450S, TRIMMAL	ard slot notspot MHz~470MHz	
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Laser Scanner Communication Sensor	evaluation Pixel Function Range Laser product classification FOV Point cloud thickness I/O Interface Network WiFi Bluetooth Internal UHF Radio Electronic bubble Tilt Survey Physical button	3 Professional Dual HD Cameras Support AR stakeout, image measurement, worki 40m Class 1 Eye Safe H: 160° V: 59° 2cm USB type C port; SMA antenna port; Nano SIM ca TDD-LTE, FDD-LTE, GSM IEEE 802.11a/b/g/n/ac/ax, 2.4GHz/5GHz, Wifi h Bluetooth 5.2 Power: 0.5W/1W Adjustable Frequence: 410M Protocol: HI-TARGET, TRIMTALK450S, TRIMMAI Channel: 116 (16 scalable) Supports Built-in High-precision IMU Module Single button 2.8 inch, 480×640 pixel touchable screen Satellite, Signal, Power	ard slot notspot MHz~470MHz	
Laser Scanner Communication Sensor Control Panel	evaluation Pixel Function Range Laser product classification FOV Point cloud thickness I/O Interface Network WiFi Bluetooth Internal UHF Radio Electronic bubble Tilt Survey Physical button Display LED lights Advanced function	3 Professional Dual HD Cameras Support AR stakeout, image measurement, worki 40m Class 1 Eye Safe H: 160° V: 59° 2cm USB type C port; SMA antenna port; Nano SIM ca TDD-LTE, FDD-LTE, GSM IEEE 802.11a/b/g/n/ac/ax, 2.4GHz/5GHz, Wifi h Bluetooth 5.2 Power: 0.5W/1W Adjustable Frequence: 410N Protocol: HI-TARGET, TRIMTALK450S, TRIMMAI Channel: 116 (16 scalable) Supports Built-in High-precision IMU Module Single button 2.8 inch, 480×640 pixel touchable screen Satellite, Signal, Power NFC, WebUI, Firmware upgrade via U-disk	ard slot notspot MHz~470MHz	
Laser Scanner Communication Sensor	evaluation Pixel Function Range Laser product classification FOV Point cloud thickness I/O Interface Network WiFi Bluetooth Internal UHF Radio Electronic bubble Tilt Survey Physical button Display LED lights Advanced function Intelligence application	3 Professional Dual HD Cameras Support AR stakeout, image measurement, worki 40m Class 1 Eye Safe H: 160° V: 59° 2cm USB type C port; SMA antenna port; Nano SIM ca TDD-LTE, FDD-LTE, GSM IEEE 802.11a/b/g/n/ac/ax, 2.4GHz/5GHz, Wifi h Bluetooth 5.2 Power: 0.5W/1W Adjustable Frequence: 410W Protocol: HI-TARGET, TRIMTALK450S, TRIMMAI Channel: 116 (16 scalable) Supports Built-in High-precision IMU Module Single button 2.8 inch, 480×640 pixel touchable screen Satellite, Signal, Power NFC, WebUI, Firmware upgrade via U-disk Intelligent Voice, Self-check	ard slot notspot MHz~470MHz	
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Laser Scanner Communication Sensor Control Panel Application	evaluation Pixel Function Range Laser product classification FOV Point cloud thickness I/O Interface Network WiFi Bluetooth Internal UHF Radio Electronic bubble Tilt Survey Physical button Display LED lights Advanced function Intelligence application Remote service Power[4] Size Weight Water/dustproof	3 Professional Dual HD Cameras Support AR stakeout, image measurement, worki 40m Class 1 Eye Safe H: 160° 2cm USB type C port; SMA antenna port; Nano SIM ca TDD-LTE, FDD-LTE, GSM IEEE 802.11a/b/g/n/ac/ax, 2.4GHz/5GHz, Wifi h Bluetooth 5.2 Power: 0.5W/1W Adjustable Frequence: 410W Protocol: HI-TARGET, TRIMTALK450S, TRIMMAI Channel: 116 (16 scalable) Supports Built-in High-precision IMU Module Single button 2.8 inch, 480×640 pixel touchable screen Satellite, Signal, Power NFC, WebUI, Firmware upgrade via U-disk Intelligent Voice, Self-check Message push, online upgrade, remote control Lithium battery, supports hot-swapping and portat RTK rover(UHF/Cellular): up to 15 hours USB 45W fast charging, fully charged in 2 hours Φ134.4mm×109.9mm ≤1.6kg IP64	ard slot notspot MHz~470MHz RK III, SATEL-3AS, TRANSEOT, etc.	

Note:

[2]The measurement accuracy, precision, reliability and initialization time depend on various factors, including tilt angle, number of satellites, geometric distribution, observation time, atmospheric conditions and multi-path validation, etc. The data are derived under normal conditions.

 $\hbox{\cite{the inertial navigation accuracy.}} \label{the inertial navigation accuracy.}$

[4] The battery operating time is related to the operating environment, operating temperature and battery life. Descriptions and Specifications are subject to change without notice